

Multiplicative deformations of the Borchers-Uhlmann algebra

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Motivation

Main focus of algebraic QFT since its invention:

- ◊ Model-independent analysis of QFT (nets of operator algebras)
- ◊ Development of tools for computing physically interesting quantities once a model is given

More recently: Construction of models with tools of algebraic QFT

This talk: Construction of models by algebraic deformation methods

Construction of QFT models via wedge algebras

Wedge algebras:

► Baumgärtel/Wollenberg 92

► Buchholz/Summers 08

Input: Hilbert space \mathcal{H} with representation U of the Poincaré group and vacuum vector Ω .

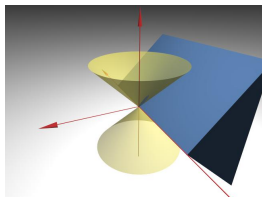
Wanted: $\mathcal{M} \subset \mathcal{B}(\mathcal{H})$ von Neumann "wedge algebra":

- ◊ $U(x, \Lambda) \mathcal{M} U(x, \Lambda)^{-1} \subset \mathcal{M}$ for $(x, \Lambda) \in \mathcal{P}_+$ with $\Lambda W_0 + x \subset W_0$
- ◊ $U(0, j) \mathcal{M} U(0, j)^{-1} \subset \mathcal{M}'$
- ◊ Ω cyclic for \mathcal{M}

with

- ◊ $W_0 = \{x \in \mathbb{R}^d : x_1 > |x_0|\} = \text{right wedge}$
- ◊ reflection

$$j(x^0, \dots, x^{d-1}) = (-x^0, -x^1, x^2, \dots, x^{d-1})$$



- ◊ With such data U, \mathcal{M} , a QFT model can be generated.

Deformations of wedge algebras

- One approach to finding such pairs U, \mathcal{M} is to start with data U_0, \mathcal{M}_0 defining a free field theory, and search for solutions U, \mathcal{M} by **deforming** $\mathcal{M}_0 \rightsquigarrow \mathcal{M}$ in a certain manner.
- A two-parameter family of solutions is known (warping)
 - ▶ Grosse/GL 07
 - ▶ Buchholz/Summers 08
 - ▶ Buchholz/GL/Summers 10
- Applications of this method:
 - ▶ Dappiaggi/GL/Morfa-Morales 10
 - ▶ Dybalski/Tanimoto 10
 - ▶ Morfa-Morales 11
- Other deformations
 - ▶ Longo/Witten 10
 - ▶ Longo/Rehren 11
 - ▶ Tanimoto ??

Here:

Many more deformations, constructed in a Wightman framework.

The Borchers-Uhlmann algebra $\underline{\mathcal{L}}$

- $\underline{\mathcal{L}} = \bigoplus_{n=0}^{\infty} \mathcal{S}_n$ with $\mathcal{S}_n := \mathcal{S}(\mathbb{R}^{nd})$, $\mathcal{S}_0 := \mathbb{C}$, as top. space.
- elements $f = (f_0, f_1, \dots, f_N, 0\dots)$, $f_n \in \mathcal{S}_n$
- product

$$(f \otimes g)_n(x_1, \dots, x_n) = \sum_{k=0}^n f_k(x_1, \dots, x_k) g_{n-k}(x_{k+1}, \dots, x_n).$$

- identity $1_n := \delta_{n,0}$
- *-involution

$$f^*_n(x_1, \dots, x_n) = \overline{f_n(x_n, \dots, x_1)}.$$

- automorphic Poincaré action

$$(\alpha_{a,\Lambda} f)_n(x_1, \dots, x_n) = \overline{f_n(\Lambda^{-1}(x_1 - a), \dots, \Lambda^{-1}(x_n - a))}$$

Products on $\underline{\mathcal{L}}$

- Deformations of algebras Gerstenhaber 64: deform the product
- product** := bilinear associative separately continuous map $\underline{\mathcal{L}} \times \underline{\mathcal{L}} \rightarrow \underline{\mathcal{L}}, f, g \mapsto f \hat{\otimes} g$ with

$$(f \hat{\otimes} g)^* = g^* \hat{\otimes} f^*, \quad f \hat{\otimes} 1 = f = 1 \hat{\otimes} f.$$

- As a tensor algebra (\cong free algebra), $\underline{\mathcal{L}}$ is **rigid**. Its products are

$$f \hat{\otimes} g = \rho^{-1}(\rho(f) \otimes \rho(g))$$

Only trivial deformations of $\underline{\mathcal{L}}$ as an associative algebra exist.

- But:** Situation very different for **nets** in $\underline{\mathcal{L}}$. Here also products $f \otimes_{\rho} g := \rho^{-1}(\rho(f) \otimes \rho(g))$ give rise to non-trivial deformations.

Deformation maps and compatible states

Definition:

A deformation map (relative to W_0) is a linear homeomorphism $\rho : \underline{\mathcal{L}} \rightarrow \underline{\mathcal{L}}$ such that

- ⬢ $\rho(1) = 1$.
- ⬢ $\rho(f)^* = \rho(f^*)$.
- ⬢ $\rho \circ \alpha_{x,\Lambda} = \alpha_{x,\Lambda} \circ \rho$ for all $(x, \Lambda) \in \mathcal{P}_+$ with $\Lambda W_0 + x \subset W_0$.

- ⬢ Deformation maps form a group \mathcal{R} .
- ⬢ ρ is **not** invariant under **all** Lorentz transformations,

$$\rho_\Lambda := \alpha_\Lambda \circ \rho \circ \alpha_\Lambda^{-1} \neq \rho.$$

- ⬢ Need to represent the different product structures \otimes_{ρ_Λ} (corresponding to different wedges) on the same Hilbert space.

Deformation maps and compatible states

Definition:

A state ω on $\underline{\mathcal{L}}$ is called **compatible** with a deformation map ρ if

$$\omega(f \otimes_{\rho} g) = \omega(f \otimes g), \quad f, g \in \underline{\mathcal{L}}.$$

Lemma:

Let ρ be a deformation map and ω a ρ -compatible state. Then ω is also a state on $(\underline{\mathcal{L}}, \otimes_{\rho})$, and the GNS triples $(\mathcal{H}_{\omega}, \phi_{\omega}, \Omega_{\omega})$ of $(\underline{\mathcal{L}}, \otimes)$ and $(\mathcal{H}_{\omega}^{\rho}, \phi_{\omega}^{\rho}, \Omega_{\omega}^{\rho})$ of $(\underline{\mathcal{L}}, \otimes_{\rho})$ are related by

$$\begin{aligned} \mathcal{H}_{\omega}^{\rho} &= \mathcal{H}_{\omega}, \\ \Omega_{\omega}^{\rho} &= \Omega_{\omega}, \\ \phi_{\omega}^{\rho}(f)\phi_{\omega}(g)\Omega_{\omega} &= \phi_{\omega}(f \otimes_{\rho} g)\Omega_{\omega}, \quad f, g \in \underline{\mathcal{L}}. \end{aligned}$$

Deformation maps and compatible states

A ρ -compatible Poincaré invariant state ω defines deformed fields

$$\phi_{\omega}^{\rho_{\Lambda}}(f), \quad f \in \underline{\mathcal{L}}, \quad \rho_{\Lambda} := \alpha_{\Lambda} \circ \rho \circ \alpha_{\Lambda}^{-1},$$

as operators on the GNS space of $(\underline{\mathcal{L}}, \otimes), \omega$, with

$$\begin{aligned} \phi_{\omega}^{\rho_{\Lambda}}(f)\phi_{\omega}^{\rho_{\Lambda}}(g) &= \phi_{\omega}^{\rho_{\Lambda}}(f \otimes_{\rho_{\Lambda}} g) \\ \phi_{\omega}^{\rho_{\Lambda}}(f)^* &\supset \phi_{\omega}^{\rho_{\Lambda}}(f^*) \\ U_{\omega}(x, \Lambda)\phi_{\omega}^{\rho}(f)U_{\omega}(x, \Lambda)^{-1} &= \phi_{\omega}^{\rho_{\Lambda}}(\alpha_{x, \Lambda}f) \\ \phi_{\omega}^{\rho_{\Lambda}}(f)\Omega_{\omega} &= \phi_{\omega}(f)\Omega_{\omega} \end{aligned}$$

The $*$ -algebra $\mathcal{P}_{\omega, 0}^{\rho}$ generated by all $\phi_{\omega}^{\rho}(f)$, $\text{supp } f_n \subset W_0^n$ satisfies

$$U_{\omega}(x, \Lambda)\mathcal{P}_{\omega, 0}^{\rho}U_{\omega}(x, \Lambda)^{-1} \subset \mathcal{P}_{\omega, 0}^{\rho} \text{ for } \Lambda W_0 + x \subset W_0$$

and Ω_{ω} is cyclic for $\mathcal{P}_{\omega, 0}^{\rho}$ if it is cyclic for $\mathcal{P}_{\omega, 0}^{\text{id}}$.

Procedure for deforming wedge-local QFT

- Find (class of) deformation maps ρ on $\underline{\mathcal{L}}$
- Find states compatible with ρ (at least free field Wightman state should be compatible)
- Adjust ρ and ω in such a way that ρ is wedge-local in ω :

$$[\phi_\omega^\rho(f), \phi_\omega^{\rho_j}(g)]\Psi = 0,$$

$$f \in \underline{\mathcal{L}}(W_0), g \in \underline{\mathcal{L}}(jW_0), \Psi \in \phi_\omega(\underline{\mathcal{L}})\Omega_\omega.$$

- Possibly proceed to von Neumann algebras of bounded functions of field operators, $\mathcal{M}_\omega^\rho := \{\exp i\phi_\omega^\rho(f) : f \in \underline{\mathcal{L}}_{\mathbb{R}}(W_0)\}''$.
- Then $\mathcal{M}_\omega^\rho, U_\omega$ satisfy our requirements, and generate a QFT.

Rest of the talk: Carry out this program for a simple class of ρ 's.

Multiplicative deformations

- A deformation map is called **multiplicative** (in momentum space) if it has the form

$$\widetilde{\rho}(f)_n(p_1, \dots, p_n) = \rho_n(p_1, \dots, p_n) \cdot \tilde{f}_n(p_1, \dots, p_n).$$

→ abelian subgroup of deformations $\mathcal{R}_0 \subset \mathcal{R}$.

Lemma:

For ρ to be a deformation map, the ρ_n must be smooth and satisfy

- polynomial bounds from above and below on their derivatives
- For each Lorentz transformation Λ with $\Lambda W_0 = W_0$,

$$\rho_n(\Lambda p_1, \dots, \Lambda p_n) = \rho_n(p_1, \dots, p_n).$$

- $\overline{\rho_n(-p_n, \dots, -p_1)} = \rho_n(p_1, \dots, p_n)$ (for $(f \otimes_\rho g)^* = g^* \otimes_\rho f^*$)
- $\rho_0 = 1$ (for $f \otimes_\rho 1 = f = 1 \otimes_\rho f$)

Multiplicative deformations and compatible states

- The deformed product associated with $\rho \in \mathcal{R}_0$ is

$$(\widetilde{f \otimes_{\rho} g})_n(p_1, \dots, p_n) = \sum_{k=0}^n \rho_{kn}(p_1, \dots, p_n) \cdot \tilde{f}_k(p_1, \dots, p_k) \tilde{g}_{n-k}(p_{k+1}, \dots, p_n)$$

$$\text{with } \rho_{kn}(p_1, \dots, p_n) := \frac{\rho_k(p_1, \dots, p_k) \rho_{n-k}(p_{k+1}, \dots, p_n)}{\rho_n(p_1, \dots, p_n)}$$

- Can take $\rho_1(p_1) = 1$ without loss of generality.
- Compatible states: Need

$$\begin{aligned} & \int d\mathbf{p} \tilde{\omega}_n(-p_1, \dots, -p_n) \rho_{kn}(p_1, \dots, p_n) \tilde{f}_k(p_1, \dots, p_k) \tilde{g}_{n-k}(p_{k+1}, \dots, p_n) \\ &= \int d\mathbf{p} \tilde{\omega}_n(-p_1, \dots, -p_n) \tilde{f}_k(p_1, \dots, p_k) \tilde{g}_{n-k}(p_{k+1}, \dots, p_n) \end{aligned}$$

Multiplicative deformations and compatible states

- If $\rho \in \mathcal{R}_0$ is compatible with all **translationally invariant states**, then

$$\rho_n(p_1, \dots, p_n) = \rho_k(p_1, \dots, p_k) \rho_{n-k}(p_{k+1}, \dots, p_n)$$

for all $k \in \{1, \dots, n-1\}$ and $p_1 + \dots + p_n = 0$.

- One solution is known (warped convolution)
- More solutions? ... [▶ Alazzawi](#)

Deformation two-point functions

Proposition:

Let $\rho_2 \in C^\infty(\mathbb{R}^d \times \mathbb{R}^d)$ be a two-point function of a multiplicative deformation satisfying

$$\rho_2(p, -p) = 1, \quad \rho_2(-p, q) = \rho_2(p, -q) = \rho_2(q, p) = \rho_2(p, q)^{-1}.$$

Define

$$\rho_0 := 1, \quad \rho_1(p_1) := 1, \quad \rho_n(p_1, \dots, p_n) = \prod_{1 \leq l < r \leq n} \rho_2(p_l, p_r), \quad n \geq 2.$$

Then

- ◊ The ρ_n define a multiplicative deformation $\rho \in \mathcal{R}_0$.
- ◊ ρ is compatible with all **quasi-free** translationally inv. states ω .

Problem of finding deformations reduced to two-point function ρ_2 .

Definition:

A **deformation function** is a smooth function $R : \mathbb{R} \rightarrow \mathbb{C}$, polynomially bounded in all derivatives, such that

- ⬢ $R(a)^{-1} = \overline{R(a)} = R(-a)$, $R(0) = 1$.
- ⬢ The Fourier transform \tilde{R} of R has support on the positive half line.
- ⬢ Support restriction on $\tilde{R} \Leftrightarrow$ analyticity and boundedness of R .
- ⬢ Examples:

$$R(a) = e^{ica} \prod_{k=1}^N \frac{z_k - a}{z_k + a}, \quad c \geq 0, \operatorname{Im} z_1, \dots, \operatorname{Im} z_N \geq 0$$

These functions appear in many places ▶ Longo/Witten 10 ▶ Longo/Rehren 11

- ⬢ Special case: $R(a) = e^{ia}$

▶ Grosse/GL 07
▶ Buchholz/Summers 08
▶ Grosse/GL 08
▶ Buchholz/GL/Summers 10

Definition

A real $(d \times d)$ -matrix Q is called **admissible** ▶ Buchholz/GL/Summers 10 if

- ◊ Q is antisymmetric w.r.t. the Minkowski inner product
- ◊ $\Lambda Q \Lambda^{-1} = \begin{cases} Q & ; \Lambda \in \mathcal{L}_+^\uparrow \text{ with } \Lambda W_0 = W_0 \\ -Q & ; \Lambda \in \mathcal{L}_+^\downarrow \text{ with } \Lambda W_0 = W_0 \end{cases}$
- ◊ $QV^+ \subset W_0$.

Q must have the form

$$Q = \begin{pmatrix} 0 & \kappa & 0 & 0 \\ \kappa & 0 & 0 & 0 \\ 0 & 0 & 0 & \kappa' \\ 0 & 0 & -\kappa' & 0 \end{pmatrix} \quad \text{with } \kappa \geq 0, \kappa' \in \mathbb{R}.$$

Lemma:

Let R be a deformation function and Q an admissible matrix. Then the deformation two-point function

$$\rho_2(p, q) := R(-p \cdot Qq)$$

defines a multiplicative deformation $\rho(R, Q) \in \mathcal{R}_0$ compatible with all quasi-free translationally invariant states.

◉ Transformation law:

$$\alpha_{x, \Lambda}(f \otimes_{\rho(R, Q)} g) = \alpha_{x, \Lambda}(f) \otimes_{\rho(R, \pm \Lambda Q \Lambda^{-1})} \alpha_{x, \Lambda}(g)$$

Wedge-Locality

Theorem:

Let R be a deformation function, and Q an admissible matrix. Then the deformation $\rho(R, Q)$ is wedge-local in any quasi-free Wightman state.

Important ingredients of proof:

- Need to show that for $f \in \underline{\mathcal{L}}(W_0)$, $g' \in \underline{\mathcal{L}}(W'_0)$, $h, k \in \underline{\mathcal{L}}$,

$$\omega((h \otimes_{\rho} f) \otimes (g' \otimes_{\rho'} k)) = \omega((h \otimes_{\rho'} g') \otimes (f \otimes_{\rho} k)).$$

- The automorphisms

$$(\widetilde{\tau_x^R f})_n(p_1, \dots, p_n) := \prod_{k=1}^n R(x \cdot p_k) \cdot \tilde{f}_n(p_1, \dots, p_n)$$

satisfy

$$\tau_x^R(\underline{\mathcal{L}}(W_0)) \subset \underline{\mathcal{L}}(W_0) \text{ for } x \in \overline{W_0},$$

$$\text{supp}(h_m \otimes_{\rho} f_n) \subset \mathbb{R}^{md} \times W_0^n \text{ for } \text{supp } \tilde{h}_m \subset V_-^m, \quad \text{supp } f_n \subset W_0^n.$$

Fock space representations

- Quasi-free Wightman state $\omega \rightarrow$ Fock space \mathcal{H}_ω as GNS space.
- If $\tilde{\omega}_2(p, q) = \delta(p + q)\delta(p^0 - \varepsilon_p)\varepsilon_p^{-1}$, $\varepsilon_p = (p^2 + m^2)^{1/2}$, $m > 0$, then ϕ_ω is the scalar massive Klein-Gordon field.

Deformed field $\phi_{R,Q} := \phi_\omega^{\rho(R,Q)}$ satisfies by construction:

- $U(x, \Lambda)\phi_{R,Q}(f)U(x, \Lambda)^{-1} = \phi_{R, \Lambda Q \Lambda^{-1}}(\alpha_{x, \Lambda} f)$ for $(x, \Lambda) \in \mathcal{P}_+^\uparrow$.
- $U(0, j)\phi_{R,Q}(f)U(0, j)^{-1} = \phi_{R, -Q}(\alpha_j f)$.
- $[\phi_{R,Q}(f), \phi_{R,-Q}(g)]\Psi = 0$ for $f \in \mathcal{L}(W_0)$, $g \in \mathcal{L}(W'_0)$, $\Psi \in \mathcal{D}$.
- still solves Klein-Gordon equation
- $\lambda \mapsto \phi_{R, \lambda \cdot Q}(f)\Psi$ continuous, $\Psi \in \mathcal{D}$. In particular

$$\lim_{\lambda \rightarrow 0} \phi_{R, \lambda \cdot Q}(f)\Psi = \phi(f)\Psi.$$

Von Neumann algebras and modular data

With $\mathcal{P}_R(\Lambda W_0 + x) :=$ *-alg. gen. by $\phi_{R, \Lambda Q \Lambda^{-1}}(f)$, $f \in \underline{\mathcal{L}}(\Lambda W_0 + x)$,

$$W \longmapsto \mathcal{P}_R(W)$$

is an isotonus, covariant, (wedge-) local net of *-algebras satisfying the Reeh-Schlieder property.

- Passage to von Neumann algebras $\mathcal{M}_R(W)$ possible here (essentially self-adjoint field operators).
- Ω is cyclic and separating for $\mathcal{M}_R(W_0)$, with modular data independent of R .
- Infinite family of solutions to inverse problem in modular theory
▶ Wollenberg
- Ω is not cyclic for spacelike cones.

Deformed field operators

- Explicit realization of deformed fields: Replace creation/annihilation operators $a^\#(p)$ by

$$a_{R,Q}(p) := a(p) T_R(Qp), \quad a_{R,Q}^\dagger(p) := a^\dagger(p) T_R(-Qp),$$

$$(T_R(x)\Psi)_n(q_1, \dots, q_n) := \prod_{k=1}^n R(x \cdot q_k) \cdot \Psi_n(q_1, \dots, q_n).$$

- For $f_1 \in \mathcal{S}_1$, the deformed fields take the form

$$\phi_{R,Q}(f_1) = (2\pi)^{-d} \int dp dx e^{-ip \cdot x} U(x, 1) \phi(f_1) U(-x, 1) T_R(-Qp)$$

Formula similar to warped convolution, but not valid for higher tensors $f_n \in \mathcal{S}_n$, $n > 1$.

Two-particle scattering

- The S-matrix for $2 \rightarrow 2$ processes can be calculated. For $f_1, g_1, h_1, k_1 \in \mathcal{S}_1$ with velocity supports $\Gamma(f_1) - \Gamma(g_1) \subset W_0$, $\Gamma(h_1) - \Gamma(k_1) \subset W_0$,

$$\begin{aligned} & \langle f_1^+ \times_{\text{out}}^R g_1^+, h_1^+ \times_{\text{in}}^R k_1^+ \rangle \\ &= \int d\mu(p_1) d\mu(p_2) R(-p_1 \cdot Qp_2)^2 \overline{\tilde{f}_1(p_1)} \overline{\tilde{g}_1(p_2)} \tilde{h}_1(p_1) \tilde{k}_1(p_2). \end{aligned}$$

- Phase shift effect, no particle production
- S-matrix fully Lorentz invariant only in $d = 1 + 1$
- The deformation function is the root of the two-particle S-matrix

Deformations of QFTs and integrable models

- When deforming in $d = 1 + 1$, one obtains integrable models.
- rapidity-parametrized on-shell momenta $p(\theta) = m(\cosh \theta, \sinh \theta)$ lead to

$$S(\theta_1 - \theta_2) := R(-p(\theta_1) \cdot Qp(\theta_2))^2 = R(\kappa m^2 \sinh(\theta_1 - \theta_2))^2$$

with the usual unitarity, analyticity, crossing relations of the scattering function S .

- Deformed ann./creation operators \rightarrow **Zamolodchikov algebra**
- Same structure as in algebraic construction of integrable models

▶ Schroer 97

▶ Schroer 00

▶ GL 03

▶ Buchholz/GL 04

▶ GL 06

Theorem:

Every 2d integrable QFT with scattering function S of the above form arises from a free field theory by deformation. If S is **regular**, then the deformed theory satisfies Reeh-Schlieder for double cones above a minimal size ▶ L 06.

Conclusion

- Multiplicative deformations: Large family of new QFT deformations
- Lead to wedge-local covariant models in any dimension
- In $d = 1 + 1$, provide deformations of free field theories into fully local integrable QFTs
- In $d > 1 + 1$, more complicated deformations (non-multiplicative) for more realistic interaction needed (particle production).
- Need deformation maps of the form

$$\widetilde{\rho}(f)_n(p_1, \dots, p_n) = \sum_{m=0}^{\infty} \int dq_1 \dots dq_m \rho_{nm}(p_1, \dots, p_n; q_1, \dots, q_m) \tilde{f}_m(q_1, \dots, q_m)$$

- More complicated, but might give interacting models in $d > 1 + 1$ (wedge-local fields no longer polarization-free)